## ENGR 695 Advanced Topics in Engineering Mathematics Fall 2023

## Lecture Outline for Friday, Aug. 25

- 1. Basic problems and computations in linear algebra:  $A\mathbf{x} = \mathbf{b}$  [review]
  - a. A, x given: geometric transformations (images, outputs from inputs)
  - b. *A*, **b** given: system solution (inputs from outputs)
  - c. Size & shape matter in defining the solution
- 2. Solution of  $A\mathbf{x} = \mathbf{b}$  using the inverse. For an  $N \times N$  (square) system, the following statements are equivalent for the purpose of determining the solvability of the problem.
  - a.  $A\mathbf{x} = \mathbf{b}$  has a unique solution
  - b. A has a unique inverse  $(A^{-1})$
  - c. A is non-singular
  - d. A has full rank (i.e., rank(A) = N)
  - e.  $\det(A) = |\mathbf{A}| \neq 0$
- 3. Route to finding solutions (implicit inverse computation)
  - a. Process: for augmented matrix and reduce (transform) a system to an easier-to-solve form
  - b.  $A\mathbf{x} = \mathbf{b}$  becomes  $U\mathbf{x} = \mathbf{d}$  and solution ensues (U is upper triangular)
  - c. Method: row reduction using elementary row operations (EROs); Gaussian elimination or Gauss-Jordan elimination
    - i. Multiply a row (*j*) by a value (*c*)
    - ii. Add a multiple (c) of one row (j) to another (k)
    - iii. Interchange rows j and k

## Example Problems in Solving Systems of Linear Equations

Prob. 1:

 $3x_1 - x_2 + x_3 = -1$   $9x_1 - 2x_2 + x_3 = -9$  $3x_1 + x_2 - 2x_3 = -9$ 

Prob. 2:

3x - y - 2z = 0-6x + 2y + 6z = 42x + y + 6z = 13