

Lecture Outline for Monday, Dec. 4

1. Review/help session scheduling (final exam is 11:45 am – 2:45 pm Wednesday, Dec. 13):
 - a. Review: Any time Monday, Dec. 11 or ending before 4:30 pm Tuesday, Dec. 12
 - b. Tentative help session schedule:
 - Monday, Dec. 11, 9:00–10:00 pm (Zoom)
 - Tuesday, Dec. 12, 1:00–2:00 pm (BRKI 368) – depends on review session timing
 - Wednesday, Dec. 13, 10:00–11:00 am (BRKI 368)
2. Review sheet for final exam posted soon. Exam covers material since Midterm Exam.
3. Correction to answer given for HW #8 Prob. 2 (Robin boundary condition in the Crank-Nicholson heat equation algorithm)

- a. Robin boundary condition:

$$\left. \frac{\partial u}{\partial x} \right|_{x=a} - hu(a, t) \approx \frac{u(a + \Delta x, j\Delta t) - u(a - \Delta x, j\Delta t)}{2\Delta x} - hu(a, j\Delta t) = -hu_m$$

FD approximation simplifies to

$$u_{0,j} = u_{2,j} - 2\Delta x h u_{1,j} + 2\Delta x h u_m$$

- b. Regular update equation applied at location $i = 1$

$$u_{0,j+1} - \alpha u_{1,j+1} + u_{2,j+1} = -u_{0,j} + \beta u_{1,j} - u_{2,j}$$

where

$$\alpha = 2 \left(1 + \frac{\Delta x^2}{c\Delta t} \right) \quad \text{and} \quad \beta = 2 \left(1 - \frac{\Delta x^2}{c\Delta t} \right)$$

- c. After substitution to eliminate $u_{0,j}$ and $u_{0,j+1}$:

$$(u_{2,j+1} - 2\Delta x h u_{1,j+1} + 2\Delta x h u_m) - \alpha u_{1,j+1} + u_{2,j+1} = -(u_{2,j} - 2\Delta x h u_{1,j} + 2\Delta x h u_m) + \beta u_{1,j} - u_{2,j}$$

$$\rightarrow -(\alpha + 2\Delta x h)u_{1,j+1} + 2u_{2,j+1} = (\beta + 2\Delta x h)u_{1,j} - 2u_{2,j} - 4\Delta x h u_m,$$

not

$$-(\alpha + 2\Delta x h)u_{2,j+1} + 2u_{3,j+1} = (\beta + 2\Delta x h)u_{2,j} - 2u_{3,j} - 4\Delta x h u_m$$

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- d. The special update equation for the Robin BC at $x = a$ involves terms at $i = 1$ and $i = 2$, and the special update equation at $x = b$ involves terms at $i = N_x - 1$ and $i = N_x$. The total number of equations is therefore equal to N_x , which results in an $N_x \times N_x$ system of equations, compared to the $(N_x - 2) \times (N_x - 2)$ system for Dirichlet BCs. (The system for Neumann BCs is also $N_x \times N_x$ in size.)

- e. Can express the system of equations for Robin BCs as

$$\mathbf{A}\mathbf{u}_{j+1} = \mathbf{B}\mathbf{u}_j + \mathbf{c} \rightarrow \mathbf{u}_{j+1} = \mathbf{A}^{-1}\mathbf{B}\mathbf{u}_j + \mathbf{A}^{-1}\mathbf{c} \rightarrow \mathbf{u}_{j+1} = \mathbf{D}\mathbf{u}_j + \mathbf{d},$$

where $\mathbf{D} = \mathbf{A}^{-1}\mathbf{B}$, $\mathbf{d} = \mathbf{A}^{-1}\mathbf{c}$,

$$\mathbf{A} = \begin{bmatrix} -(\alpha + 2\Delta x h) & 2 & 0 & 0 & \cdots & 0 \\ 1 & -\alpha & 1 & 0 & \cdots & 0 \\ 0 & 1 & -\alpha & 1 & & \vdots \\ \vdots & & & \ddots & & 0 \\ 0 & \cdots & 0 & 1 & -\alpha & 1 \\ 0 & \cdots & 0 & 0 & 2 & -(\alpha + 2\Delta x h) \end{bmatrix}, \quad \mathbf{u}_{j+1} = \begin{bmatrix} u_{1,j+1} \\ u_{2,j+1} \\ u_{3,j+1} \\ \vdots \\ u_{N_x-1,j+1} \\ u_{N_x,j+1} \end{bmatrix}, \quad \mathbf{u}_j = \begin{bmatrix} u_{1,j} \\ u_{2,j} \\ u_{3,j} \\ \vdots \\ u_{N_x-1,j} \\ u_{N_x,j} \end{bmatrix},$$

$$\mathbf{B} = \begin{bmatrix} \beta + 2\Delta x h & -2 & 0 & 0 & \cdots & 0 \\ -1 & \beta & -1 & 0 & \cdots & 0 \\ 0 & -1 & \beta & -1 & & \vdots \\ \vdots & & & \ddots & & 0 \\ 0 & \cdots & 0 & -1 & \beta & -1 \\ 0 & \cdots & 0 & 0 & -2 & \beta + 2\Delta x h \end{bmatrix}, \quad \text{and} \quad \mathbf{c} = \begin{bmatrix} -4\Delta x h u_m \\ 0 \\ 0 \\ \vdots \\ 0 \\ -4\Delta x h u_m \end{bmatrix}.$$

- f. Not required in Prob.2, but for reference: Derivation of special update equation at $x = b$ for Robin BC (note sign changes; see p. 714 in Sec. 13.2 of Zill, 6th ed.):

$$\left. \frac{\partial u}{\partial x} \right|_{x=b} + hu(b, t) \approx \frac{u(b + \Delta x, j\Delta t) - u(b - \Delta x, j\Delta t)}{2\Delta x} + hu(b, j\Delta t) = hu_m$$

FD approximation simplifies to

$$\frac{u_{N_x+1,j} - u_{N_x-1,j}}{2\Delta x} + hu_{N_x,j} = hu_m \rightarrow u_{N_x+1,j} = u_{N_x-1,j} - 2\Delta x h u_{N_x,j} + 2\Delta x h u_m$$

At time $j + 1$:

$$u_{N_x+1,j+1} = u_{N_x-1,j+1} - 2\Delta x h u_{N_x,j+1} + 2\Delta x h u_m$$

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Regular update equation applied at location $i = N_x$

$$u_{N_x-1,j+1} - \alpha u_{N_x,j+1} + u_{N_x+1,j+1} = -u_{N_x-1,j} + \beta u_{N_x,j} - u_{N_x+1,j}$$

Substitution to eliminate terms at $i = N_x + 1$:

$$u_{N_x-1,j+1} - \alpha u_{N_x,j+1} + (u_{N_x-1,j+1} - 2\Delta x h u_{N_x,j+1} + 2\Delta x h u_m) = \\ -u_{N_x-1,j} + \beta u_{N_x,j} - (u_{N_x-1,j} - 2\Delta x h u_{N_x,j} + 2\Delta x h u_m)$$

$$\rightarrow 2u_{N_x-1,j+1} - (\alpha + 2\Delta x h)u_{N_x,j+1} = -2u_{N_x-1,j} + (\beta + 2\Delta x h)u_{N_x,j} - 4\Delta x h u_m$$